

# Tranformasi Z

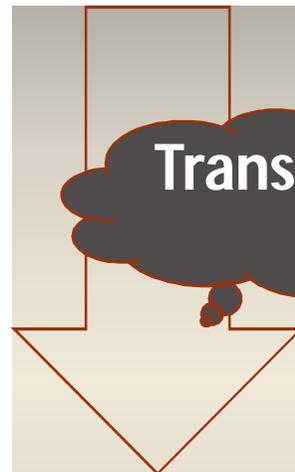
## [Sistem Kontrol Digital]

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# Mengapa diperlukan Transformasi-Z?

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**Sinyal pada domain Diskrit Time**



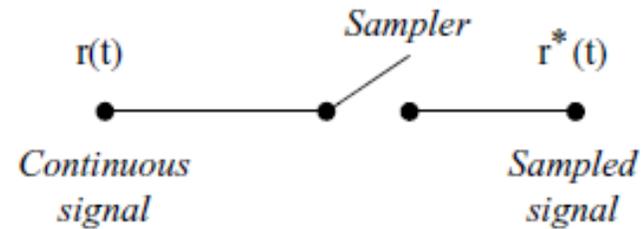
Ragazzini & Zadeh  
pada  
kontrol  
data tersampling

**Sinyal pada Domain Frekuensi**

Output dari respon sistem data tersampling dapat  
ditentukan dengan mudah

# Definisi

$$R^*(s) = \sum_{n=0}^{\infty} r(nT)e^{-snT}$$



$$e^{-snT}$$

$$Z = e^{sT}$$

**Definisi Transformasi Z**

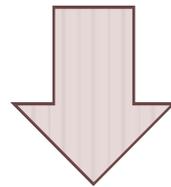
Transformasi Z dari  $r(t)$   $\Rightarrow Z[r(t)] = R(z)$

# Variabel Infinite series Transformasi-Z

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**Transformasi Z** dari  $r(t)$

$$R(z) = \sum_{n=0}^{\infty} r(nT)z^{-n}$$

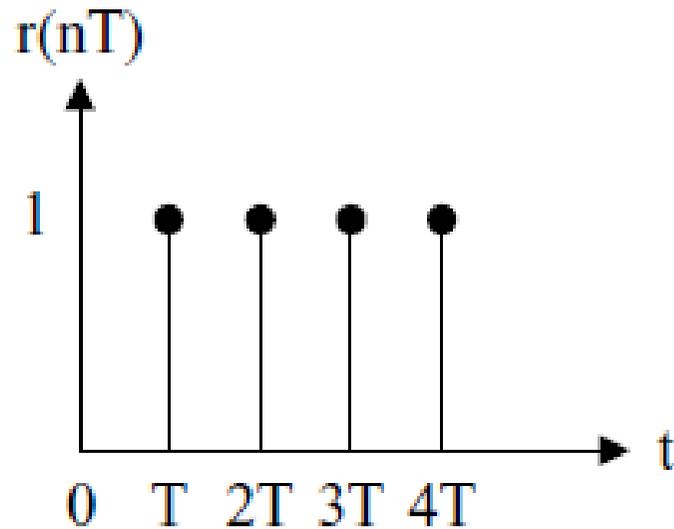


$n=0,1,2,3,\dots$

$$R(z) = r(0) + r(T)z^{-1} + r(2T)z^{-2} + r(3T)z^{-3} + \dots$$

# Fungsi Unit Step

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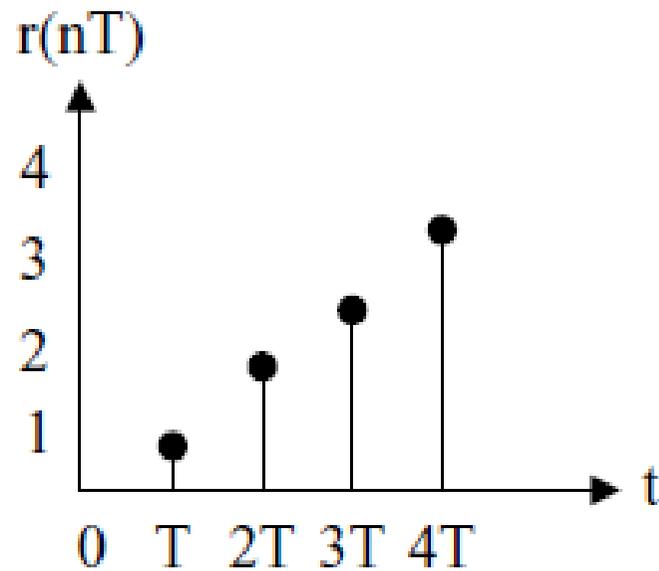


$$r(nT) = \begin{cases} 0, & n < 0, \\ 1, & n \geq 0. \end{cases}$$

$$R(z) = \sum_{n=0}^{\infty} r(nT)z^{-n} = \sum_{n=0}^{\infty} z^{-n} = 1 + z^{-1} + z^{-2} + z^{-3} + z^{-4} + \dots$$

$$R(z) = \frac{z}{z-1}, \quad \text{for } |z| > 1$$

# Fungsi Unit Ramp

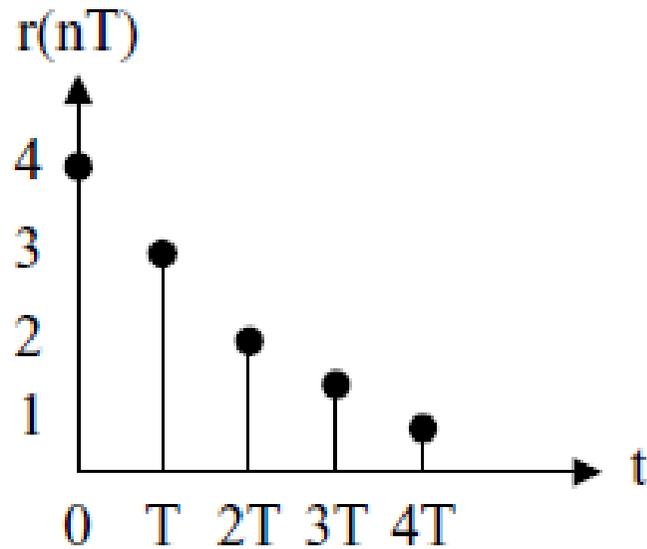


$$r(nT) = \begin{cases} 0, & n < 0, \\ nT, & n \geq 0. \end{cases}$$

$$R(z) = \sum_{n=0}^{\infty} r(nT)z^{-n} = \sum_{n=0}^{\infty} nTz^{-n} = Tz^{-1} + 2Tz^{-2} + 3Tz^{-3} + 4Tz^{-4} + \dots$$

$$R(z) = \frac{Tz}{(z-1)^2}, \quad \text{for } |z| > 1.$$

# Fungsi Eksponensial



$$r(nT) = \begin{cases} 0, & n < 0, \\ e^{-anT}, & n \geq 0. \end{cases}$$

$$R(z) = \sum_{n=0}^{\infty} e^{-anT} z^{-n} = 1 + e^{-aT} z^{-1} + e^{-2aT} z^{-2} + e^{-3aT} z^{-3} + \dots$$

$$R(z) = \frac{1}{1 - e^{-aT} z^{-1}} = \frac{z}{z - e^{-aT}}, \quad \text{for } |z| < e^{-aT}$$

# Fungsi Eksponensial Umum

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$$r(n) = \begin{cases} 0, & n < 0, \\ p^n, & n \geq 0. \end{cases}$$

$$R(z) = \sum_{n=0}^{\infty} r(nT)z^{-n} = \sum_{n=0}^{\infty} p^n z^{-n} = 1 + pz^{-1} + p^2 z^{-2} + p^3 z^{-3} + \dots$$

$$R(z) = \frac{z}{z - p}, \quad \text{for } |z| < |p|$$

$$R(p^{-k}) = \frac{z}{z - p^{-1}}$$

# Fungsi Sinus

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$$r(nT) = \begin{cases} 0, & n < 0, \\ \sin n\omega T. & n \geq 0. \end{cases} \quad \sin x = \frac{e^{jx} - e^{-jx}}{2j}$$

$$r(nT) = \frac{e^{jn\omega T} - e^{-jn\omega T}}{2j} = \frac{e^{jn\omega T}}{2j} - \frac{e^{-jn\omega T}}{2j}$$

$$R(z) = \frac{1}{2j} \left( \frac{z}{z - e^{j\omega T}} - \frac{z}{z - e^{-j\omega T}} \right) = \frac{1}{2j} \left( \frac{z(e^{j\omega T} - e^{-j\omega T})}{z^2 - z(e^{j\omega T} + e^{-j\omega T}) + 1} \right)$$

$$R(z) = \frac{z \sin \omega T}{z^2 - 2z \cos \omega T + 1}$$

# Fungsi Cosinus

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$$r(nT) = \begin{cases} 0, & n < 0, \\ \cos n\omega T, & n \geq 0. \end{cases} \quad \cos x = \frac{e^{jx} + e^{-jx}}{2}$$

$$r(nT) = \frac{e^{jn\omega T} + e^{-jn\omega T}}{2} = \frac{e^{jn\omega T}}{2} + \frac{e^{-jn\omega T}}{2}$$

$$R(z) = \frac{1}{2} \left( \frac{z}{z - e^{j\omega T}} + \frac{z}{z - e^{-j\omega T}} \right)$$

$$R(z) = \frac{z(z - \cos \omega T)}{z^2 - 2z \cos \omega T + 1}$$

# Fungsi Impulse Diskrit

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$$\delta(n) = \begin{cases} 1, & n = 0, \\ 0, & n \neq 0. \end{cases}$$

$$R(z) = \sum_{n=0}^{\infty} r(nT)z^{-n} = \sum_{n=0}^{\infty} z^{-n} = 1$$

# Fungsi Impulse Diskrit Tunda

$$\delta(n - k) = \begin{cases} 1, & n = k > 0, \\ 0, & n \neq k. \end{cases}$$

$$R(z) = \sum_{n=0}^{\infty} r(nT)z^{-n} = \sum_{n=0}^{\infty} z^{-n} = z^{-k}$$

# Tabel Transformasi Z

$f(kT)$	$F(z)$
$\delta(t)$	1
1	$\frac{z}{z-1}$
$kT$	$\frac{Tz}{(z-1)^2}$
$e^{-akT}$	$\frac{z}{z-e^{-aT}}$
$kT e^{-akT}$	$\frac{Tze^{-aT}}{(z-e^{-aT})^2}$
$a^k$	$\frac{z}{z-a}$
$1 - e^{-akT}$	$\frac{z(1-e^{-aT})}{(z-1)(z-e^{-aT})}$
$\sin akT$	$\frac{z \sin aT}{z^2 - 2z \cos aT + 1}$
$\cos akT$	$\frac{z(z - \cos aT)}{z^2 - 2z \cos aT + 1}$

# Properti Transformasi Z

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## Linearitas

$$Z[f(nT) \pm g(nT)] = Z[f(nT)] \pm Z[g(nT)] = F(z) \pm G(z)$$

$$Z[af(nT)] = aZ[f(nT)] = aF(z)$$

## Pergeseran ke Kiri $y(nT) = f(nT + mT)$

$$Y(z) = z^m F(z) - \sum_{i=0}^{m-1} f(iT)z^{m-i}$$

$$f(iT) = 0, i = 0, 1, 2, \dots, m - 1$$

$$Z[f(nT + mT)] = z^m F(z)$$

# Properti Transformasi Z

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Pergeseran ke Kanan  $y(nT) = f(nT - mT)$

$$Y(z) = z^{-m} F(z) + \sum_{i=0}^{m-1} f(iT - mT) z^{-i}$$

$f(nT) = 0$  for  $k < 0$ ,

$$Z[f(nT - mT)] = z^{-m} F(z)$$

Attenuation

$$Z[e^{-anT} f(nT)] = F[ze^{aT}]$$

# Properti Transformasi Z

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## Teorema Nilai Awal

$$\lim_{n \rightarrow 0} f(nT) = \lim_{z \rightarrow \infty} F(z)$$

## Teorema Nilai Akhir

$$\lim_{n \rightarrow \infty} f(nT) = \lim_{z \rightarrow 1} (1 - z^{-1})F(z)$$

# Contoh #1

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Tentukan Transformasi Z dari  $5r(nT)$  jika Transformasi Z dari  $r(T)$  adalah

$$R(z) = \frac{Tz}{(z-1)^2}$$

Solusi:

Dipecahkan dengan properti LINEARITAS

$$Z[5r(nT)] = 5R(z) = \frac{5Tz}{(z-1)^2}$$

## Contoh #2

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Jika Transformasi Z dari  $r(nT) = \sin n\omega T$

$$R(z) = \frac{z \sin \omega T}{z^2 - 2z \cos \omega T + 1}$$

Tentukan transformasi Z dari  $y(nT) = e^{-2T} \sin n\omega T$

**Solusi:**

Dipecahkan dengan properti Attenuasi

$$Z[y(nT)] = Z[e^{-2T} r(nT)] = R[ze^{2T}]$$

## Contoh #2

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**Solusi:**  $y(nT) = e^{-2T} \sin nWT$     $R(z) = \frac{z \sin wT}{z^2 - 2z \cos wT + 1}$

Maka:

$$\begin{aligned} Z[y(nT)] &= \frac{ze^{2T} \sin wT}{(ze^{2T})^2 - 2ze^{2T} \cos wT + 1} \\ &= \frac{ze^{2T} \sin wT}{z^2 e^{4T} - 2ze^{2T} \cos wT + 1} \end{aligned}$$

$$Z[y(nT)] = \frac{ze^{-2T} \sin wT}{z^2 - 2ze^{-2T} + e^{-4T}}$$

# Latihan

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Jika suatu fungsi adalah

$$G(z) = \frac{0.792z}{(z-1)(z^2 - 0.416z + 0.208)}$$

Dengan teorema nilai akhir, tentukan  $g(nT)$